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Ultra Reliable Low Latency Routing in LEO Satellite Constellations: A Stochastic Geometry Approach

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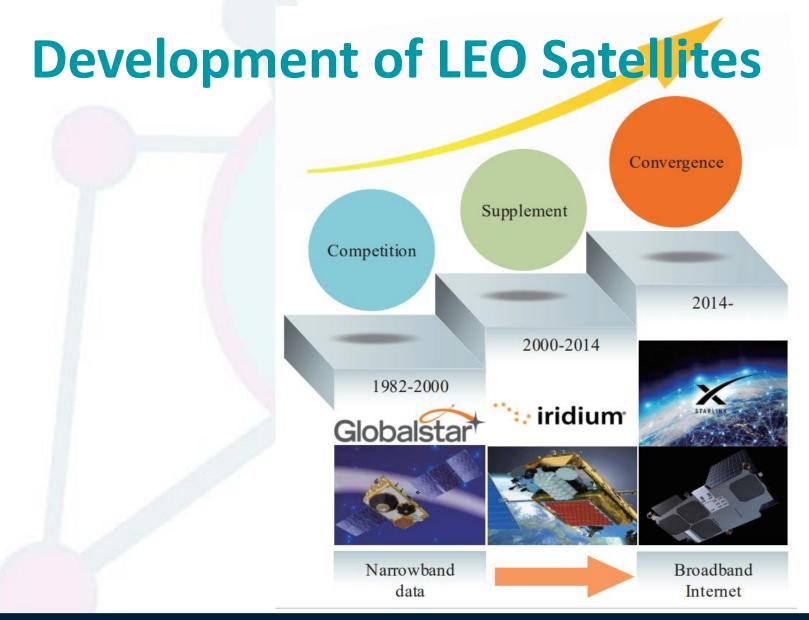


OUTLINE

1. Motivation

- 2. SG-Based Satellite Routing
- **3. System-Level Metrics**
- 4. Optimization Problems
- **5. Performance Evluation for Algorithms**
- 6. Numerical Simulation



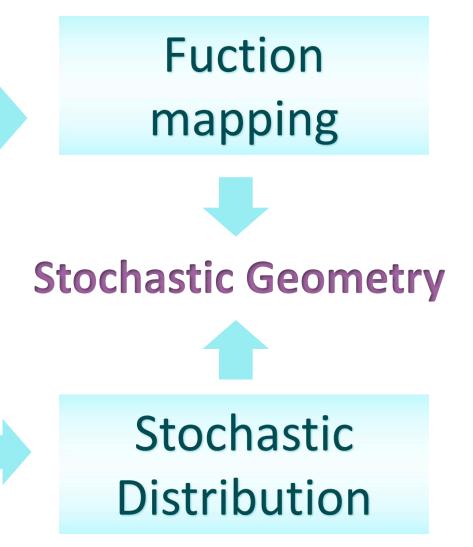




The state of the art

Graph theory model: based-on deterministic network topologies. Not suitable for dynamic networks.

Random algorithms: difficult to be supported by theoretical analysis, high complexity.





BPP Model

Tractable and accurate

Orbit geometry model

Binomial point process



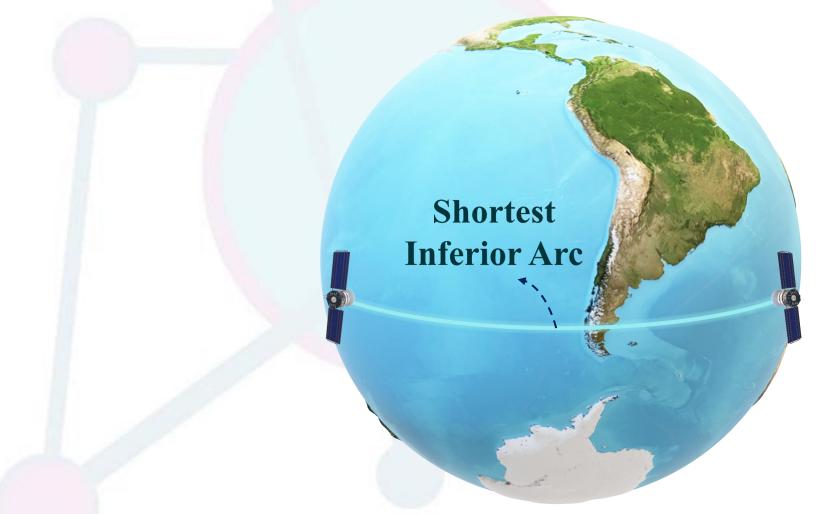
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Step 1: Find the Shortest Inferior Arc



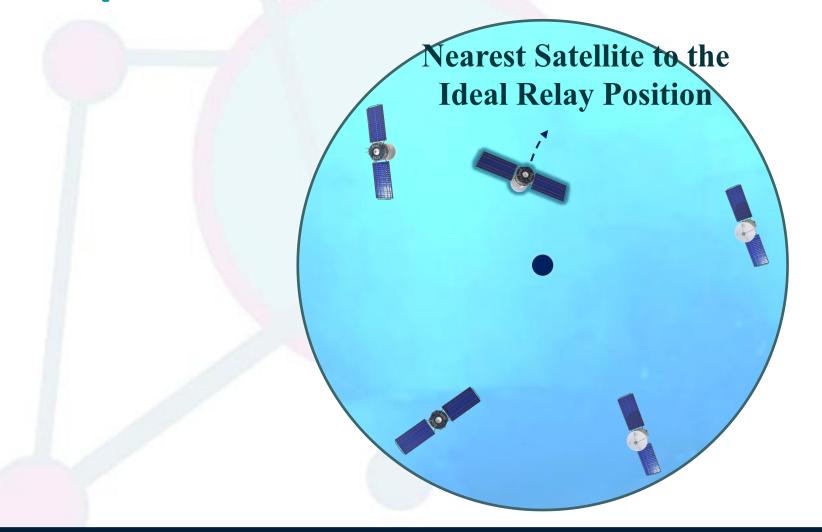


Step 2: Obtain Ideal Relay Positions





Step 3: Select the Nearest Satellite





Issues for Step 1

Shortest Inferior Arc



Issues for Step 2

What is the optimal number of hops?

Depends on system-level metrics

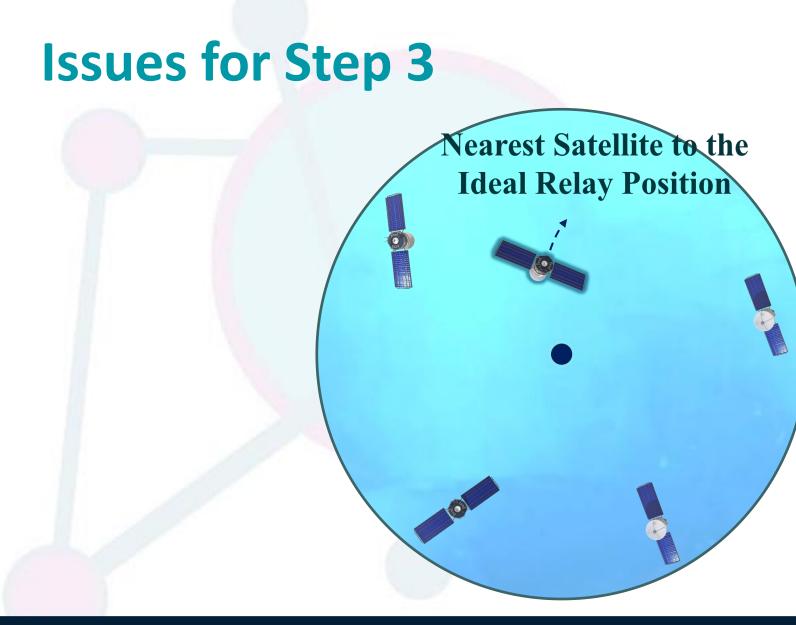


Where are optimal relay positions?



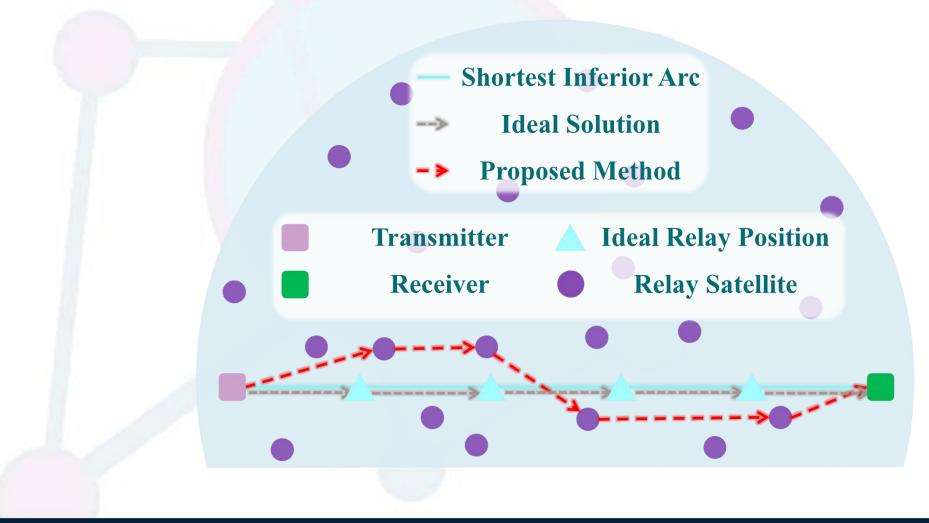
Proposition: Distributed **at equal intervals** for intersatellite routing







Distance scaling factor





Distance scaling factor

 $\alpha = \frac{Average \ distance \ in \ BPP}{Average \ distance \ in \ ideal \ scenario}$

$$\alpha^{(1)}(\theta_i) = \frac{N_s}{8\pi R_s \sin\frac{\theta_i}{2}} \int_0^{2\pi} \int_0^{\pi} \sin\xi \left(\frac{1+\cos\xi}{2}\right)^{N_s-1} \times d\left(\theta_i, 0; \xi, \varphi\right) d\xi d\varphi, \quad i = \{1, N_l\},$$

 $\alpha^{(2)}(\theta_i) = 2\alpha^{(1)}(\theta_i) - 1 \text{ (called additive evaluation)}$ $\alpha^{(2)}(\theta_i) = (\alpha^{(1)}(\theta_i))^2 \text{ (called multiplicative evaluation)}$



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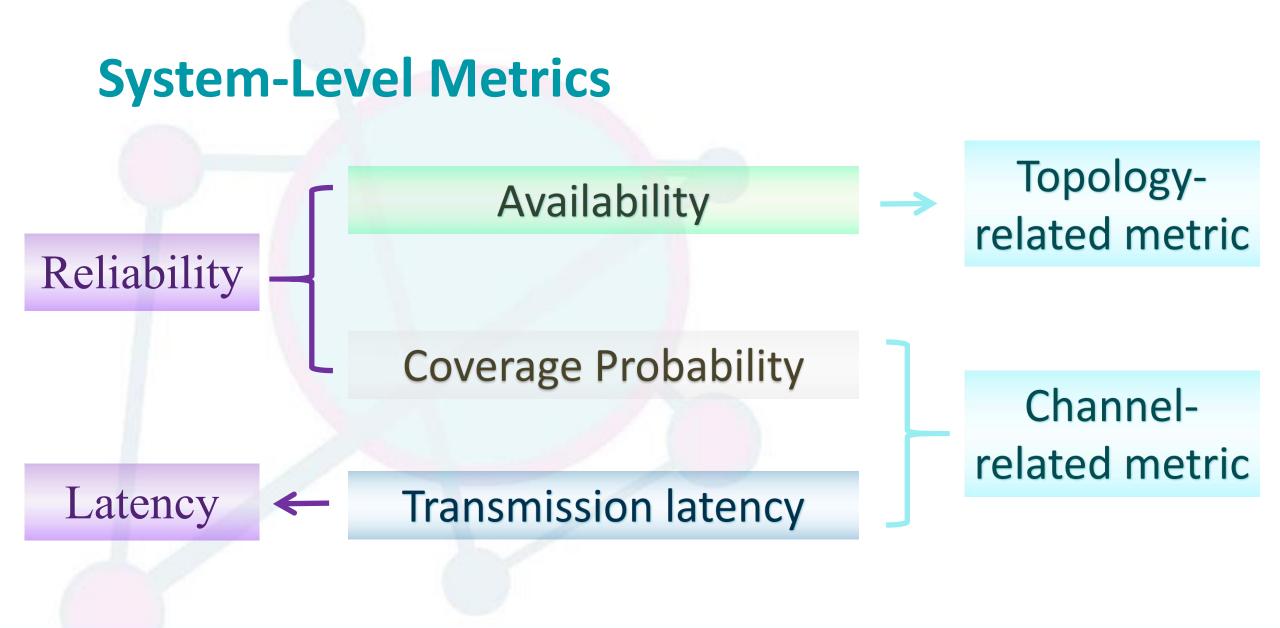


Issues for Step 2

What is the optimal number of hops?

Depends on system-level metrics Ideal Relay Position

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Availability

Every relay satellite in the route is in the communication range (not blocked by the Earth) of its last hop and next hop

$$\max_{N_l, \mathcal{M}_{|N_l}} \prod_{i=1}^{N_l} \mathbb{1}\left\{l_i \le 2\sqrt{R_s^2 - R_\oplus^2}\right\}$$



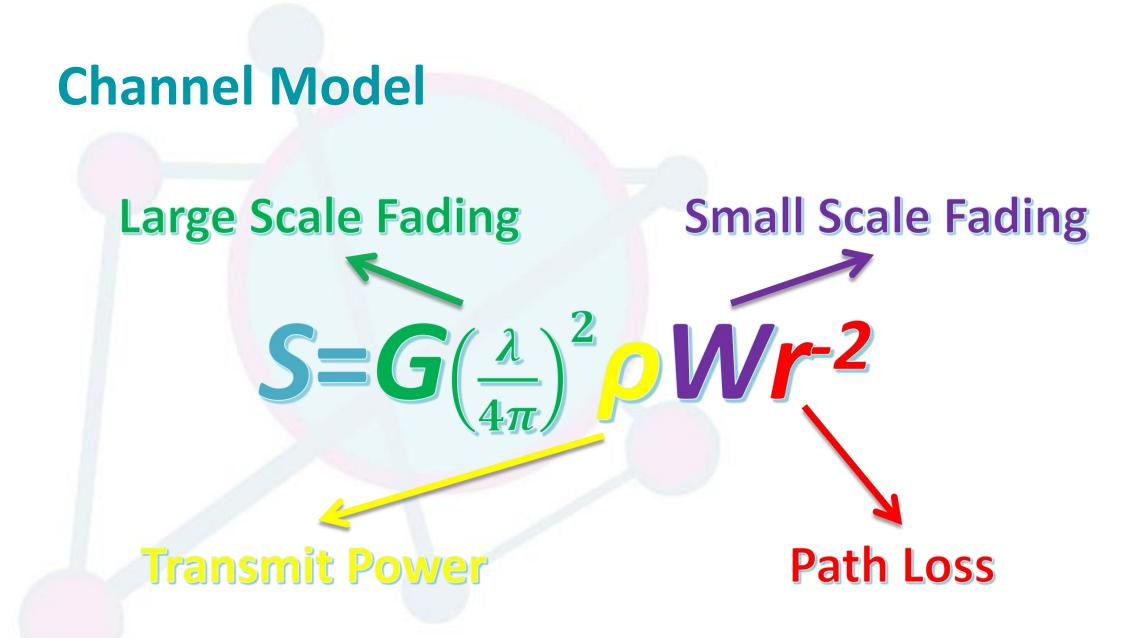
System-Level Metrics

Coverage Probability

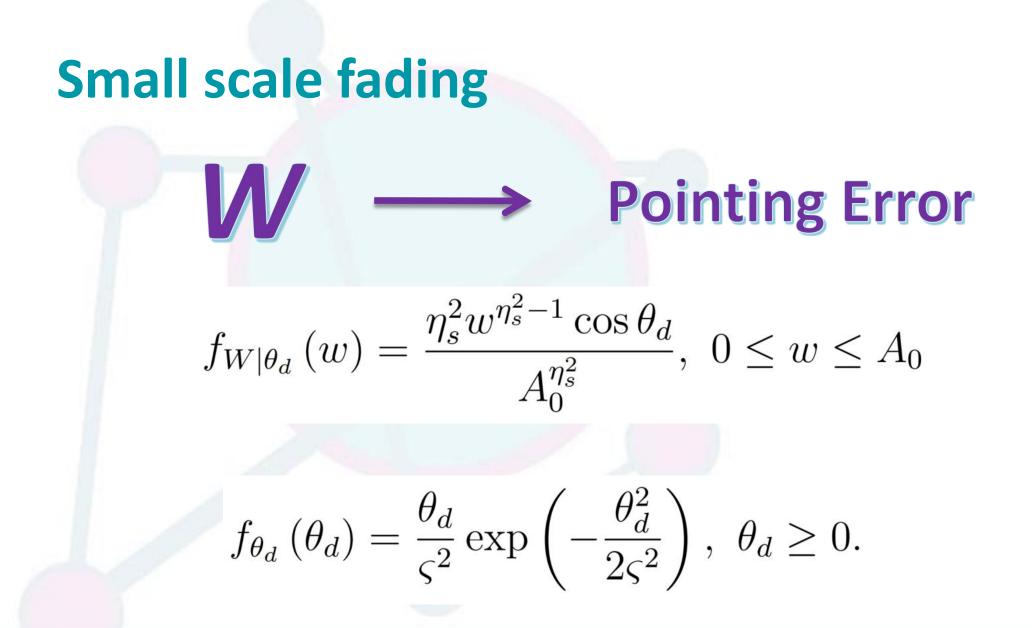
Transmission latency

Channelrelated metric











Channel-Related Metrics

SNR: The signal-to-noise ratio



SNR

Coverage Probability: the probability of successful signal demodulation at the receiver



Transmission latency: latency required for the data packet transmission at the achievable channel capacity



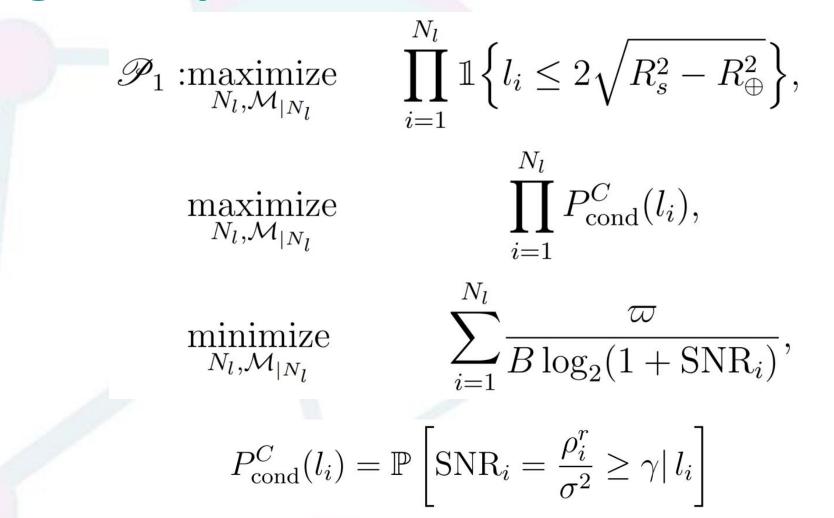
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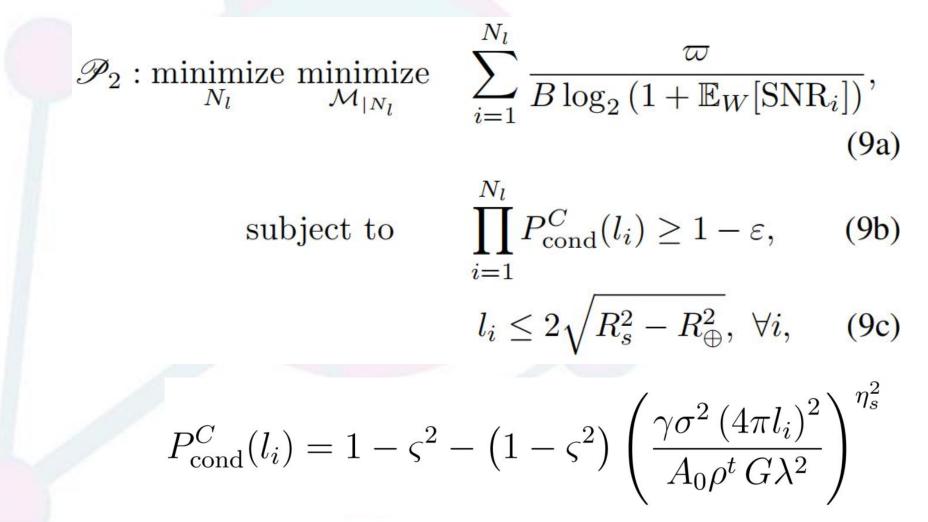


Original Optimization Problem





Method 1 : Optimization with Constrains





Method 2 : Optimization Through Mutual Relations

$$\mathscr{P}_{3} : \underset{\mathcal{M}_{|N_{l}}}{\operatorname{minimize}} \quad \underset{N_{l}}{\operatorname{minimize}} \quad T_{\mathrm{ARQ}} = \sum_{i=1}^{N_{l}} \frac{1}{P_{i}^{A,C}} \left(\frac{\varpi}{B \log_{2} \left(1 + \mathrm{SNR}_{i} \right)} \right)$$

Automatic repeat request (ARQ) protocol: the receiver respond with "successful" when packet is received; the transmitter sends the packet repeatedly without waiting until "successful" is received.

 $P_i^{A,C}$ is the probability that the ith hop is available, and its received SNR is greater than the coverage threshold



Problem Solving

- 1: Input: Locations of satellites \mathcal{X} .
- 2: Obtain optimal number of hops N_l^* through Algorithm 1 3: for $i = 1 : N_l^* - 1$ do
- 4: $m_i \leftarrow \arg\min_{1 \le n \le N_s} d\left(i \times \frac{\Theta}{N_l}, 0; \psi_n, \phi_n\right).$ 5: $\mathcal{B}_i \leftarrow \mathbb{1}\left\{d\left(\psi_{m_{i-1}}, \phi_{m_{i-1}}; \psi_{m_i}, \phi_{m_i}\right) > 2\sqrt{R_s^2 - R_{\oplus}^2}\right\}.$ 6: end for

7:
$$\mathcal{B}_{N_l^*} \leftarrow \mathbb{1}\left\{d\left(\psi_{m_{N_l^*-1}}, \phi_{m_{N_l^*-1}}; \Theta, 0\right) > 2\sqrt{R_s^2 - R_{\oplus}^2}\right\}.$$

8: $\mathcal{M}_{|N_l^*} \leftarrow \{m_1, m_2, ..., m_{N_l^*-2}, m_{N_l^*-1}\}.$

9: **Output:** IDs of relay satellites in the route $\mathcal{M}_{|N_l^*|}$

- 1: Input: Tolerable probability of communication interruption ε .
- 2: Initiate $N_l^* \leftarrow 0$ and $T_{\min} \leftarrow \infty$.

3: if
$$\frac{\Theta}{2 \arccos(R_{\oplus}/R_s)} \ge \frac{\ln(1-\varepsilon)}{\ln(1-\varsigma^2)}$$
 then

4: **Exit** the algorithm and **output** N_l^* .

5: end if 6: $N_l \leftarrow \left[\frac{\Theta}{2 \arccos(R_{\oplus}/R_s)}\right]$. 7: while $\frac{\Theta}{2 \arccos(R_{\oplus}/R_s)} \leq N_l < \frac{\ln(1-\varepsilon)}{\ln(1-\varsigma^2)}$ do 8: $N_l \leftarrow N_l + 1, \ l_{Alg1} \leftarrow 2R_s \sin \frac{\Theta}{2N_l}$. 9: if $\left(P_{\text{cond}}^C \left(\alpha^{(1)} \left(\frac{\Theta}{N_l}\right) l_{Alg1}\right)\right)^2 \times \left(P_{\text{cond}}^C \left(\alpha^{(2)} \left(\frac{\Theta}{N_l}\right) l_{Alg1}\right)\right)^{N_l-2} \geq 1-\varepsilon$ and $\alpha^{(2)} \left(\frac{\Theta}{N_l}\right) l_{Alg1} < 2\sqrt{R_s^2 - R_{\oplus}^2}$ then 10: $T_{Alg1} \leftarrow 2T_{\text{tx},1}^* \left(\alpha^{(1)} \left(\frac{\Theta}{N_l}\right) l_{Alg1}\right) + (N_l - 2) T_{\text{tx},1}^* \left(\alpha^{(2)} \left(\frac{\Theta}{N_l}\right) l_{Alg1}\right)$. 11: if $T_{\min} \geq T_{Alg1}$ then 12: $T_{\min} \leftarrow T_{Alg1}, \ N_l^* \leftarrow N_l$. 13: end if

- 13: end if
- 14: **end if**
- 15: end while
- 16: **Output**: Optimal number of hops N_l^* .



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Availability - Double Integral

$$\begin{split} P^{A} &= \left(F_{\theta_{c}^{(1)}}\left(2 \arcsin \frac{\sqrt{R_{s}^{2} - R_{\oplus}^{2}}}{R_{s}}\right)\right)^{2} \times \left(F_{\theta_{c}^{(2)}}\left(2 \arcsin \frac{\sqrt{R_{s}^{2} - R_{\oplus}^{2}}}{R_{s}}\right)\right)^{N_{l}-2} \\ F_{\theta_{c}^{(1)}}\left(\Xi\right) &= \int_{0}^{2\pi} \int_{0}^{\Xi} \frac{N_{s} \sin \theta}{2^{N_{s}+1}\pi} \left(1 + \cos\left(2 \arcsin \frac{d(\theta, \phi; \frac{\Theta}{N_{l}}, 0)}{2R_{s}}\right)\right)^{N_{s}-1} \mathrm{d}\theta \mathrm{d}\phi \end{split}$$

$$\begin{split} F_{\theta_{c}^{(2)}}\left(\Xi\right) &= F_{\theta_{c}^{(1)}}\left(2 \arcsin \frac{\sin(\Xi/2)}{\alpha^{(1)}\left(\Theta/N_{l}\right)}\right) \end{split}$$



Coverage Probability - Double Integral

$$P_{\text{rout}}^{C} = \left(\int_{0}^{\pi} f_{\theta_{c}^{(1)}}(\theta) P_{\text{cond}}^{C} \left(2R_{s} \sin \frac{\theta}{2}\right) \mathrm{d}\theta\right)^{2} \times \left(\int_{0}^{\pi} f_{\theta_{c}^{(2)}}(\theta) P_{\text{cond}}^{C} \left(2R_{s} \sin \frac{\theta}{2}\right) \mathrm{d}\theta\right)^{N_{l}-2}$$

$$f_{\theta_{c}^{(1)}}(\theta) = \int_{0}^{2\pi} \frac{N_{s} \sin \theta}{2^{N_{s}+1}\pi} \left(1 + \cos\left(2 \arcsin\frac{d(\theta, \phi; \frac{\Theta}{N_{l}}, 0)}{2R_{s}}\right)\right)^{N_{s}-1} \mathrm{d}\phi$$

$$f_{\theta_{c}^{(2)}}(\theta) = f_{\theta_{c}^{(1)}}\left(2 \arcsin\frac{\sin(\theta/2)}{\alpha^{(1)} (\Theta/N_{l})}\right) \frac{\cos(\theta/2)}{\sqrt{(\alpha^{(1)} (\Theta/N_{l}))^{2} - \sin^{2}(\theta/2)}}$$



Transmission Latency - Triple Integral

$$\overline{T}_{tx} = 2 \int_0^{\pi} \int_0^{A_0} \int_0^{\infty} \varpi f_{\theta_c^{(1)}}(\Xi) f_{W|\theta_d}(w) f_{\theta_d}(\theta_d) B^{-1} \log_2 \left(1 + \rho^t G\left(\frac{\lambda}{8\pi R_s \sin\frac{\Xi}{2}}\right)^2 \sigma^{-2} w \right)^{-1} \mathrm{d}\theta_d \,\mathrm{d}w \,\mathrm{d}\Xi$$
$$+ (N_l - 2) \int_0^{\pi} \int_0^{A_0} \int_0^{\infty} \varpi f_{\theta_c^{(2)}}(\Xi) f_{W|\theta_d}(w) f_{\theta_d}(\theta_d) B^{-1} \log_2 \left(1 + \rho^t G\left(\frac{\lambda}{8\pi R_s \sin\frac{\Xi}{2}}\right)^2 \sigma^{-2} w \right)^{-1} \mathrm{d}\theta_d \,\mathrm{d}w \,\mathrm{d}\Xi,$$

Computationally complex



Approximate Transmission Latency - Single Integral

$$\widetilde{T}_{\mathrm{tx}} = 2 \int_0^{\pi} f_{\theta_c^{(1)}}(\theta) T_{\mathrm{tx},1}^* \left(2R_s \sin\frac{\theta}{2} \right) \mathrm{d}\theta + (N_l - 2) \int_0^{\pi} f_{\theta_c^{(2)}}(\theta) T_{\mathrm{tx},1}^* \left(2R_s \sin\frac{\theta}{2} \right) \mathrm{d}\theta$$

$$T_{\text{tx},1}^*\left(l_i\right) = \frac{\varpi}{B\log_2\left(1 + \rho^t G\left(\frac{\lambda}{4\pi l_i}\right)^2 \frac{A_0\eta_s^2}{1 + \eta_s^2} \left(1 - \varsigma^2\right)\sigma^{-2}\right)}$$

We approximate it by considering the case where equality holds in Jensen's inequality
 We prove that Jensen's gap decreases as the SNR increases



ARQ Latency

$$\overline{T}_{\mathrm{ARQ}} = 2 \int_{0}^{A_{0}} \int_{0}^{\infty} \int_{0}^{\theta_{\mathrm{max}}} \frac{\overline{\varpi} f_{\theta_{c}^{(1)}}(\Xi) f_{W|\theta_{d}}(w) f_{\theta_{d}}(\theta_{d})}{P_{\mathrm{cond}}^{C} \left(2R_{s} \sin \frac{\Xi}{2}\right) B \log_{2} \left(1 + \rho^{t} G \left(\frac{\lambda}{8\pi R_{s} \sin \frac{\Xi}{2}}\right)^{2} \sigma^{-2} w\right)} \mathrm{d}\Xi \,\mathrm{d}\theta_{d} \,\mathrm{d}w$$

$$+ (N_{l} - 2) \int_{0}^{A_{0}} \int_{0}^{\infty} \int_{0}^{\theta_{\mathrm{max}}} \frac{\overline{\varpi} f_{\theta_{c}^{(2)}}(\Xi) f_{W|\theta_{d}}(w) f_{\theta_{d}}(\theta_{d})}{P_{\mathrm{cond}}^{C} \left(2R_{s} \sin \frac{\Xi}{2}\right) B \log_{2} \left(1 + \rho^{t} G \left(\frac{\lambda}{8\pi R_{s} \sin \frac{\Xi}{2}}\right)^{2} \sigma^{-2} w\right)} \mathrm{d}\Xi \,\mathrm{d}\theta_{d} \,\mathrm{d}w$$

$$\widetilde{T}_{\mathrm{ARQ}} = 2 \int_{0}^{\theta_{\mathrm{max}}} f_{\theta_{c}^{(1)}}(\theta) \frac{T_{\mathrm{tx},1}^{*} \left(2R_{s} \sin \frac{\theta}{2}\right)}{P_{\mathrm{cond}}^{C} \left(2R_{s} \sin \frac{\theta}{2}\right)} \mathrm{d}\theta + (N_{l} - 2) \int_{0}^{\theta_{\mathrm{max}}} f_{\theta_{c}^{(2)}}(\theta) \frac{T_{\mathrm{tx},1}^{*} \left(2R_{s} \sin \frac{\theta}{2}\right)}{P_{\mathrm{cond}}^{C} \left(2R_{s} \sin \frac{\theta}{2}\right)} \mathrm{d}\theta.$$



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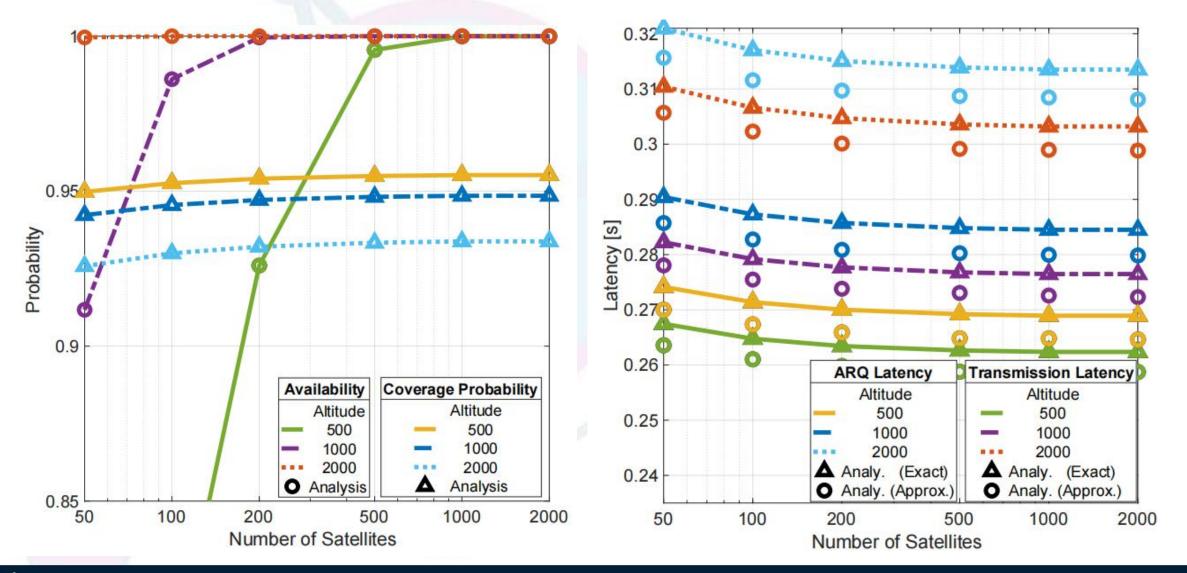


Results of Deterministic Constellations

Constellation	Starlink	Kuiper	OneWeb
Number of satellites	11927	3236	648
Altitude [km]	550	610	1200
Interference $\times 10^{-16}$ [mw]	27.81	5.359	0.908
Noise [mw]	10^{-10}		
Optimal number of hops (method I)	5	5	6
Optimal number of hops (method II)	5	5	6
Availability (Simu. & Analy.)	1.000	1.000	1.000
Coverage probability (Simu. & Analy.)	0.909	0.908	0.907
Transmission latency [s] (Simu. & Analy.)	0.642	0.645	0.741
Approx. transmission latency [s] (Analy.)	0.628	0.632	0.729
Propagation latency [s] (Simu.)	0.071	0.072	0.079
ARQ latency [s] (Simu. & Analy.)	0.654	0.658	0.754
Approx. ARQ latency [s] (Analy.)	0.641	0.645	0.741



Constellation Configuration Design





Strategies Comparison



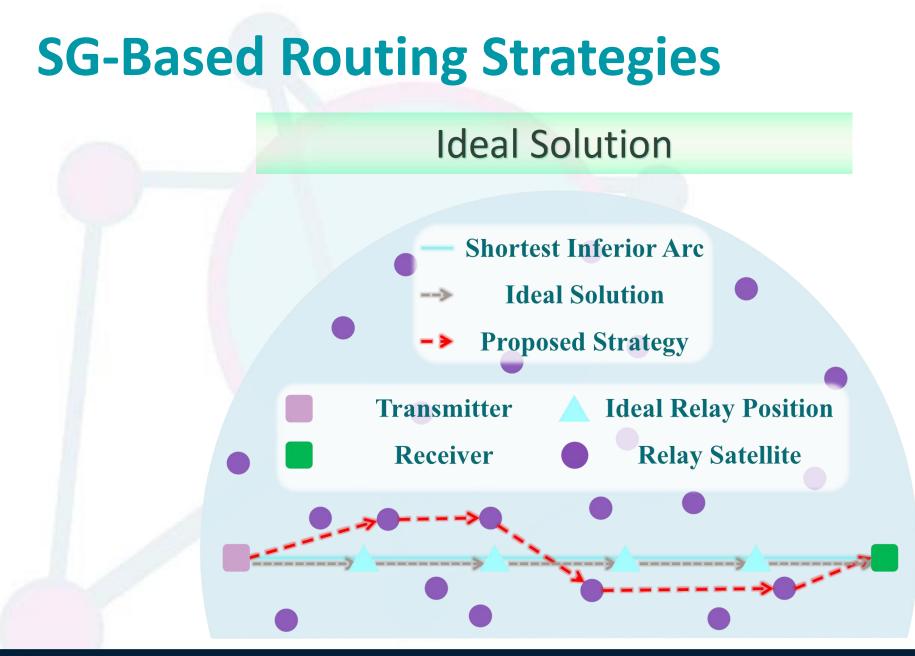
Proposed Strategy

Minimum Deflection Angle

Maximum Stepsize (Greedy)

Minimum Stepsize

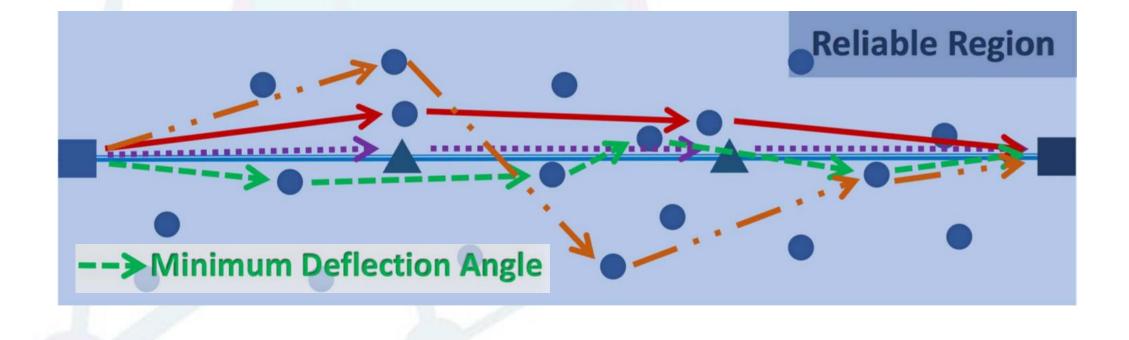






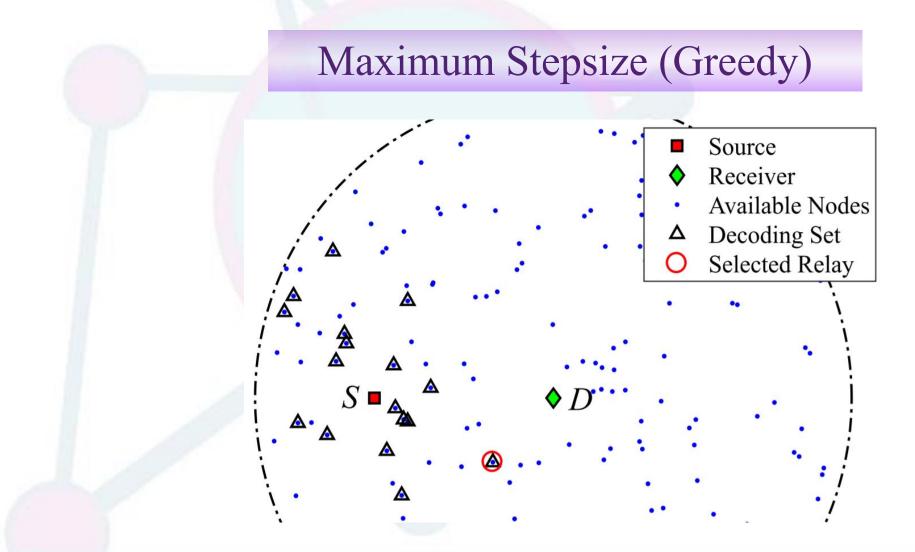
SG-Based Routing Strategies

Minimum Deflection Angle



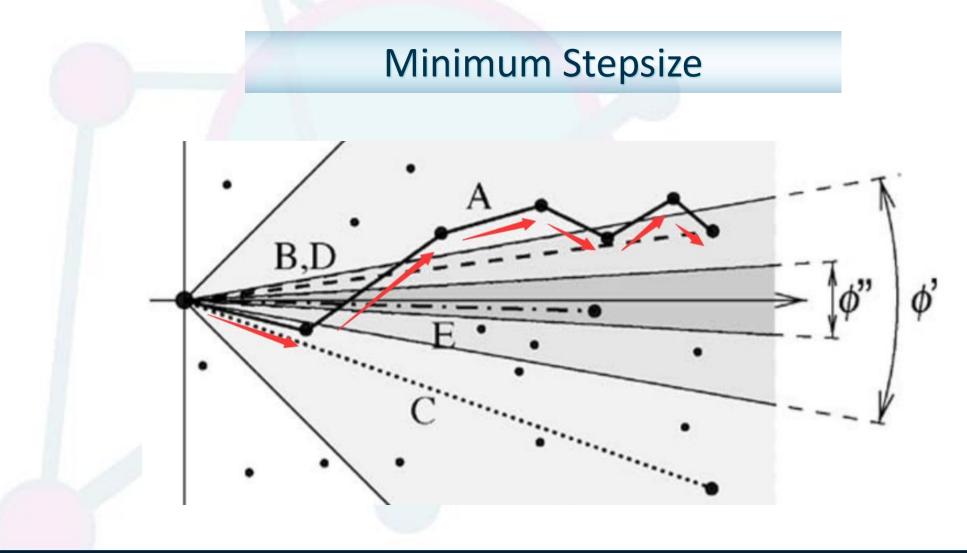


SG-Based Routing Strategies



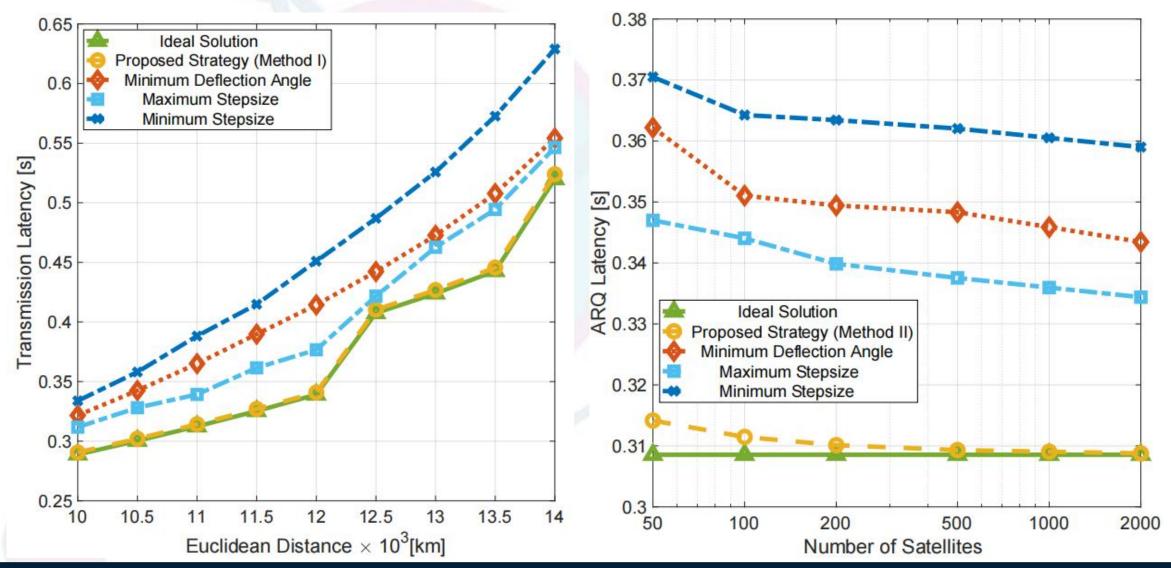


SG-Based Routing Strategies



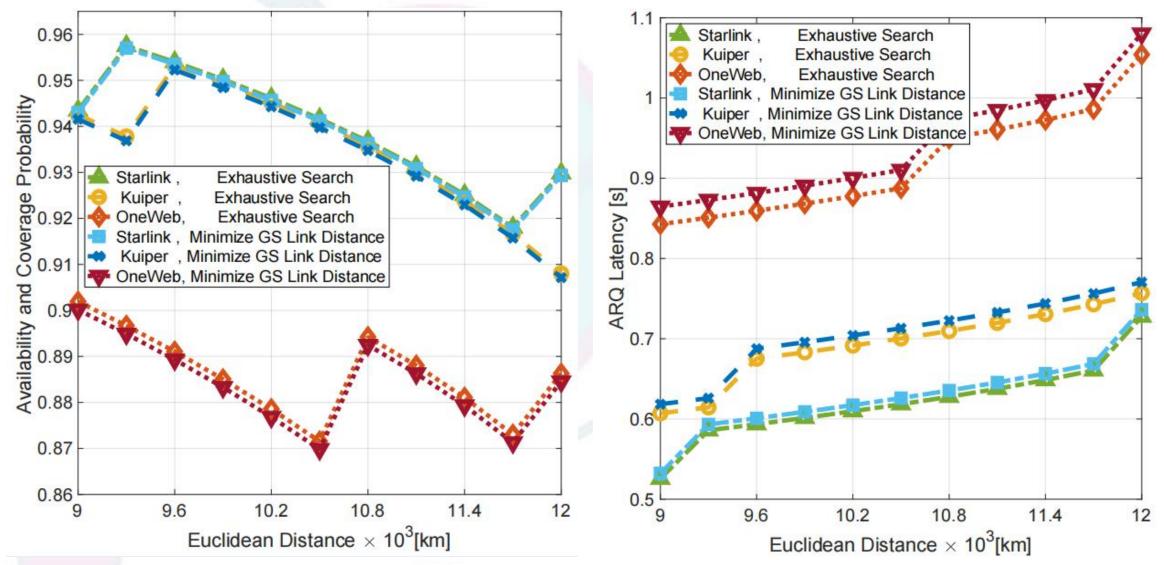


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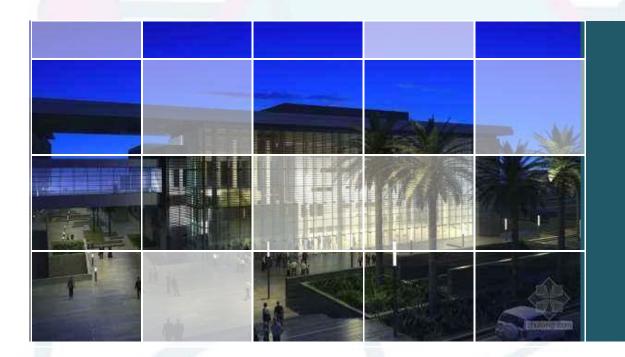
Extension to Satellite-Terrestrial Communication







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Thank You !



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